Proposed interface for Standard ML Stream I/O

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November 3, 1994

1 Introduction

The Input/Output interface provides:

- buffered reading and writing;
- arbitrary lookahead, using an underlying "lazy streams" mechanism;
- dynamic redirection of input or output;
- random access;
- uniform interface to text and binary data;
- layering of stream translations, through an underlying "reader/writer" interface;
- unbuffered input/output, through the reader/writer interface or even through the buffered stream interface;
- primitives sufficient to construct facilities for random access reading/writing to the same file.

In addition, the prescriptions and recommendations herein allow for efficient implementation, minimizing system calls and memory-memory copying.

The I/O system has several layers of interface. From bottom to top, they are

PRIM_IO Uniform interface for unbuffered reading and writing at the "system call" level, though not necessarily via actual system calls.

- **STREAM_IO** Buffered "lazy functional stream" input; buffered conventional output.
- **IO** Buffered, conventional (side-effecting) input and output with redirection facility.

Because most programmers will use the IO interface, I will describe that first, rather informally. Then I will go bottom-up over the entire system, giving a technical specification of the interfaces, and their axioms and pragmatics.

2 IO

Conventional buffered input/output is done using several structures matching the IO signature: TextIO, for character input/output, BinIO, for binary (byte) input/output.

```
signature IO =
 sig
     type instream
     type outstream
     type elem
     type vector
                    : string -> instream
     val open_in
     val close_in
                      : instream -> unit
     val input
                      : instream -> vector
                    : instream -> vector
     val input_all
     val input_noblock : instream -> vector option
                   : instream -> elem option
     val input1
     val input_n
                      : instream * int -> vector
     val end_of_stream : instream -> bool
     val lookahead : instream -> elem option
                        : instream * int -> unit (* may raise Io *)
     val setpos_in
                       : instream -> int (* always succeeds *)
     val getpos_in
     val open_out : string -> outstream
     val close_out : outstream -> unit
     val output
                  : (outstream * vector) -> unit
     val output1
                  : outstream * elem -> unit
     val flush_out : outstream -> unit
     val getpos_out : outstream -> int
     val setpos_out : outstream * int -> unit
     structure StreamIO : STREAM_IO
     sharing type elem = StreamIO.elem
     sharing type vector = StreamIO.vector
                       : StreamIO.instream -> instream
     val mk_instream
     val get_instream : instream -> StreamIO.instream
```

```
val set_instream : instream * StreamIO.instream -> unit
     val mk_outstream : StreamIO.outstream -> outstream
     val get_outstream : outstream -> StreamIO.outstream
     val set_outstream : outstream * StreamIO.outstream -> unit
  end
signature TEXT_IO =
 sig
     include IO
    sharing type StreamIO.elem = Word8.word
    sharing type StreamIO.vector = Word8Vector.vector
    val std_in : instream
    val std_out: outstream
    val std_err: outstream
 end
signature BIN_IO =
sig
    include IO
    sharing type StreamIO.elem=Word8.word
    sharing type StreamIO.vector=Word8Vector.vector
end
structure TextIO : TEXT_IO
structure BinIO : BIN_IO
```

Operations on instreams

elem

A single element (member of a stream); for **TextIO** streams this is **char**; for **BinIO** this is **Word8.word**.

vector

A sequence of elements (such as string or Word8Vector.vector).

 $f = open_in(s)$

Opens a file named s as a stream f.

$close_in(f)$

Close f; no further operations are permitted on f (they will raise the Io exception).

 $v = \mathbf{input}(f)$

Read some elements of f, returning a vector v. If (and only if) f is at end

of file, size(v) = 0. May block (not return until data is available in the external world).

$v = input_all(f)$

Return the vector v of all the elements of f up to end of stream.

$input_noblock(f)$

If any elements of f can be read without blocking, return at least one of them. If it is possible to determine without blocking that f is at end of stream, return SOME(*empty*). Otherwise return NONE.

c = input1(f)

If at least one element e of f is available, return SOME(e). If f is at end of file, return the NONE. Otherwise block until one of those conditions occurs.

$v = input_n(f, n)$

If at least n elements remain before end of stream, return the first n elements. Otherwise, return the (possibly empty) sequence of elements remaining before end of stream. Blocks if necessary. (This was the behavior of the **input** function in the 1989 *Definition of Standard ML*, and pre-1.00 releases of SML/NJ.)

$end_of_stream(f)$

False if any characters are available in f; true if f is at end of stream. Otherwise blocks until one of these conditions occurs. Exactly equivalent to (size(input f)=0).

$c = \mathbf{lookahead}(f)$

Return the next character without advancing the stream; or at end of file return NONE. Multiple-character lookahead can be accomplished with the lazy functional stream interface; see section 5.

setposin(f, i)

Seek to position i in f.

getposin(f)

Tell the current position (elements since beginning of file, starting at 0) of f. Not always supported (raises Io if not supported on f).

Operations on outstreams

 $f = \mathbf{open_out}(s)$

Open (for writing) a file named s (creating it if necessary) as an outstream f.

 $close_out(f)$

Flush f's buffer and close the stream (releasing operating-system resources associated with it).

```
output(f, v)
Write the sequen
```

Write the sequence v to f.

```
output1(f, x)
```

Write the element x to f.

$flush_out(f)$

Flush f's buffer: that is, make the underlying file reflect any previous **output** operations.

```
getpos_out(f)
```

Tell the current position of f (not always supported).

```
setpos_out(f, i)
```

Seek to position i of f (not always supported).

There is also a set of primitives to relate **IO** streams to the "lazy functional streams" model of input/output; and thus to the underlying unbuffered reader/writer primitives:

StreamIO

The particular instantiation of the **STREAM_IO** interface underlying this **IO** module (i.e., streams of bytes, chars, or some other element type).

```
f = \mathbf{mk\_instream}(s)
```

Create a conventional stream f from a functional stream s.

```
s = \mathbf{get\_instream}(f)
```

Extract the functional stream s from f. This allows arbitrary lookahead; for example:

```
fun lookahead_n(f,n) =
  let val f' = mk_instream(get_instream(f))
    in input_n(f',n)
  end
```

This makes a "copy" f' of the stream f; then input operations in f' won't affect f (though setpos_in on f' may effectively close f). For more details, see the next few sections.

```
set_instream(f, s)
```

Redirect f, so that further input comes from s. For example:

```
fun from_file(g,name) =
  let val f = open_in name
    val save_std_in = get_instream std_in
    in set_instream(std_in,get_instream f);
    g();
    set_instream(std_in, save_std_in)
  end
```

For more details, see the next few sections.

```
f = \mathbf{mk\_outstream}(s)
```

Create a conventional outstream f from a **StreamIO.outstream** s. The output streams in **StreamIO** are not "functional," they are conventional streams operated on by side-effecting output. The difference between an **IO.outstream** and a **StreamIO.outstream** is that the former may be redirected using **set_outstream**. Think of the former as a **ref** of the latter.

$s = get_outstream(f)$

Extract the underlying outstream s from the redirectable outstream f. Unfortunately, s is not "pure functional," so there's no equivalent of the lookahead trick shown above. Unlike instreams, if

val f' = mk_outstream(get_outstream f)

then operations on f' are equivalent to operations on f.

```
set\_outstream(f, s)
```

Useful for redirecting output. For example,

```
fun to_file(g,name) =
  let val f = open_out name
     val save_std_out = get_outstream std_out
  in set_outstream(std_out,get_outstream f);
    g();
    set_outstream(std_out, save_std_out)
  end
```

In can be argued that this is not very elegant; the function g, instead of writing stuff to std_out, should have been parameterized (in the usual ML way) on an outstream from the very beginning. Then the get and set primitives wouldn't be needed.

3 OS

The primitive I/O (\mathbf{PrimIO}), stream I/O ($\mathbf{StreamIO}$), and standard I/O (\mathbf{IO}) packages require only these components of the OS structure:

```
structure OS : sig
    type syserror
    val noError : syserror
    exception SysErr of
    {ml_op : string,
        os_op : string,
        reason : syserror}
```

end

All "operating system" operations not listed here (reading, writing, etc.) are parametrized (in the **PrimIO.reader** and **PrimIO.writer** types) and may or may not come from the actual operating system.

4 PRIM_IO

Primitive I/O is at the level of file descriptors and system calls.

```
signature PRIM_IO =
sig
    type elem
    type vector
    type array
    exception Io of {
       ml_op
                : string,
       name
                 : string,
       os_op
               : string,
       reason : string,
        syserror : OS.syserror
     }
    type 'a buf = {
        data : 'a,
        pos : int,
        nelems : int
     }
    datatype writer = Wr of
```

```
{write_noblock: (vector buf -> int option) option,
           writea_noblock: (array buf -> int option) option,
           write_block: (vector buf -> int) option,
           writea_block: (array buf -> int) option,
           block: (unit->unit) option,
           can_output: (unit->bool) option,
           name: string,
           chunksize: int,
           close: unit -> unit,
           getpos : (unit->int) option,
           setpos : (int->unit) option,
           file : OS.file option}
datatype reader = Rd of
          {read_noblock : (int -> vector option) option,
           reada_noblock: (array buf -> int option) option,
           read_block :
                          (int -> vector) option,
           reada block:
                           (array buf -> int) option,
           block : (unit -> unit) option,
           can_input: (unit -> bool) option,
           name: string,
           chunksize: int,
           close : unit -> unit,
           getpos : (unit -> int) option,
setpos : (int -> unit) option,
           file : OS.file option,
                   : unit -> int}
           size
val open_in: string -> reader
val open_out: string -> writer
```

```
end
```

A file (device, etc.) is a sequence of "elements" (elem), which may (for example) be characters or bytes. The distinction between characters and bytes is necessary on DOS, where CR-LF is translated to LF when reading character files; or on Windows-NT where characters are 16-bits (Unicode) and bytes are 8 bits.

One typically reads or writes a sequence of elements in one system call: this sequence is the **vector** type. Sometimes it is useful to write the sequence from a mutable **array** instead of from the vector.

A reader is a file (device, etc.) opened for reading, and a writer one opened for writing.

The components of a writer are:

$write_noblock{buf=v,pos=i,nelems=n}$

This (optional) function without blocking writes elements v_i, \ldots, v_{i+k-1} , for $k \leq n$ to the output device, and returns SOME(k); or (if the write would block) returns NONE. k = 0 is not recommended (prohibited?). Raises Io on failure of underlying system call, or **Subscript** if i < 0 or i + n > length(v).

writea_noblock{buf=a,pos=i,nelems=n}

This (optional) function without blocking writes elements a_i, \ldots, a_{i+k-1} , for $k \leq n$ to the output device, and returns SOME(k); or (if the write would block) returns NONE. k = 0 is not recommended (prohibited?).

write_block{buf=v,pos=i,nelems=n}

This (optional) function writes elements v_i, \ldots, v_{i+k-1} , for $0 < k \le n$ to the output device, and returns k. If necessary, waits (blocks) until the external world can accept at least one element.

writea_block{buf=a,pos=i,nelems=n}

This (optional) function without blocking writes elements a_i, \ldots, a_{i+k-1} , for $0 < k \leq n$ to the output device, and returns SOME(k); or (if the write would block) returns NONE. If necessary, waits (blocks) until the external world can accept at least one element.

block()

This (optional) function does not return until the writer is guaranteed to be able to write without blocking.

can_output()

(optional) Returns true iff the next write can proceed without blocking.

name

The name associated with this file or device, for use in error messages shown to the user.

chunksize

The recommended (efficient) size of write operations on this writer. This is typically to the block size of the operating system's buffers. If that is not known, a value of 2048 or 4096 will probably work well. **Chunksize** = 1 strongly recommends (but cannot guarantee, since buffering occurs in other modules, not this one) unbuffered I/O on the writer. **Chunksize** \leq 0 is illegal (functions in other modules taking writers as arguments may raise exceptions).

close()

Closes the writer (for example, frees operating system resources devoted to this writer). Further operations to this writer are illegal (but it is not the responsibility of the writer to check for this).

getpos()

(optional) Tells the number of elements in the file between the beginning and the current position. (Initially, getpos() = 0.) Most useful on seekable writers.

setpos(i)

(optional) Moves to position i in the file, so future writes occur at this position.

One of **write_block** or **write_noblock** must be provided. Providing more of the optional functions increases functionality and/or efficiency of clients:

- 1. Absence of both write_block and block means that blocking output is not possible.
- 2. Absence of both write_noblock and can_output means that non-blocking output is not possible.
- 3. Absence of **write_noblock** means that non-blocking output requires two system calls (using **can_output**, **write_block**).
- 4. Absence of **writea_block** or **writea_nonblock** means that extra copying will be required to write from an array.
- 5. Absence of getpos means that buffered setpos may be less efficient.
- 6. Absence of setpos prevents random access.

The components of a **reader** are

close()

Closes the reader (for example, frees operating system resources). Further operations to this reader are illegal but need not be checked for by the reader.

name

The name associated with this file or device, for use in error messages shown to the user.

chunksize

The recommended (efficient) size of read operations on this reader. This is typically to the block size of the operating system's buffers. If that is not known, a value of 2048 or 4096 will probably work well. **Chunksize** = 1 strongly recommends (but cannot guarantee, since buffering occurs in other modules, not this one) unbuffered I/O on this reader. **Chunksize** = 0 is illegal.

$read_noblock(n)$

(optional) Reads *i* elements without blocking, for $0 < i \leq n$ creating a vector *v*, returning SOME(*v*); or (if a read would block) returns NONE.

$read_block(n)$

(optional) Reads *i* elements for $0 < i \le n$ returning a vector *v* of length *i*; blocks (waits) if necessary until at least one element is available.

$reada_noblock{buf=a,pos=i,nelems=n}$

(optional) Reads k elements without blocking, for $0 < k \leq n$ into a_i, \ldots, a_{i+k-1} , returning SOME(k); if no elements remain before end-of-file, returns SOME(0) without blocking; or (if a read would block) returns NONE.

reada_block{buf=a,pos=i,nelems=n}

(optional) Reads k elements for $0 < k \le n$ into a_i, \ldots, a_{i+k-1} , returning a vector k; blocks (waits) if necessary until at least one element is available. If no elements reamain before end-of-file, returns 0.

block()

(optional) Returns only when at least one element is available for read without blocking.

can_input()

(optional) Returns true iff the next read can proceed without blocking.

getpos()

(optional) Tells the current position in the file (0 means beginning of file). Useful even for non-seekable files, if the **size** function is provided (because large input operations are more efficient if the distance from "here to end of file" is known).

setpos(i)

(optional) Move to position i in file.

size()

Hint at the approximate total size (number of elements) of the file. If it is inconvenient to support size accurately, gross inaccuracy (even to the extent of always reporting 0) is permitted.

One of **read_block** or **read_noblock** must be provided. Providing more of the optional functions increases functionality and/or efficiency of clients:

- 1. Absence of both **read_block** and **block** means that blocking input is not possible.
- 2. Absence of both **read_noblock** and **can_input** means that non-blocking input is not possible.

- 3. Absence of **read_noblock** means that non-blocking input requires two system calls (using **can_input**, **read_block**).
- 4. Absence of **reada_noblock** or **reada_block** means that input into an array requires extra copying. But I do not anticipate that reading into arrays will normally be very important in the "lazy functional stream" model.

Clients of **PrimIO** are required to synthesize blocking reads from **read_noblock+block**, synthesize vector reads from array reads, synthesize array reads from vector reads, as needed—so the **PrimIO.reader** is required to provide only a minimum set. If the **reader** can provide more than the minimum set in a way that is more efficient then the obvious synthesis than by all means it should do so. However, providing more than the minimum by just doing (inside the PrimIO layer) the obvious synthesis is not recommended, because then clients won't get the "hint" about which are the efficient ("recommended") operations.

- 5. Inaccuracy of size means that very large inputs (where vectors must be pre-allocated) cannot be done efficiently (in one system call, without copying) if size is reported too small, or will cause excess memory allocation if size is reported too large. Recommendation: size=fn()=>0 is acceptable; an approximately accurate size is better; an accurate size is best.
- 6. Absence of getpos, in the unusual case where a buffered system is applied to a reader not positioned at the beginning of the file, may lead to excessive memory allocation of vectors for very large input operations.
- 7. Absence of getpos means that buffered setpos may be less efficient.

8. Absence of setpos prevents random access.

Any of the component functions of readers or writers may raise the Io exception. No other exceptions should be raised. The components of Io are:

ml_op

The name of the reader/writer component function raising the exception.

name

Should equal the **name** component of the reader or writer.

os_op

The name of the operating system call (if any) that failed, otherwise empty.

syserror

If the Io exception is raised as the result of handling an **OS.SysErr** exception, then the **reason** code provided by the operating system. Otherwise, **OS.noError**.

reason

If syserror \neq OS.noError, then OS.errorName(syserror); otherwise, a textual summary of the error.

The functions **open_in** and **open_out** provide system-default ways to create readers from "file names." Structures matching this signature may leave these two functions unimplemented (by having them raise the **Io** exception) if there is no appropriate system default.

5 STREAM_IO

The Stream I/O interface provides buffered reading and writing to input and output streams.

Input streams are treated in the lazy functional style: that is, input from a stream f yields a finite vector of elements, plus a new stream f'. Input from f again will yield the same elements; to advance within the stream in the usual way it is necessary to do further input from f'. This interface allows arbitrary lookahead to be done very cleanly, which should be useful both for *ad hoc* lexical analysis and for table-driven, regular-expression-based lexing.

Output streams are handled more conventionally, since the lazy functional style doesn't seem to make sense for output.

```
signature STREAM_IO =
sig
   structure PrimIO: PRIM_IO
   type elem sharing type elem = PrimIO.elem
   type vector sharing type vector = PrimIO.vector
   type instream
   type outstream
   val open_in : string -> instream
   val mk_instream : PrimIO.reader * string -> instream
   val close_in : instream -> unit
   val setpos_in
                     : instream * int -> instream
   val getpos_in
                     : instream -> int
                    : instream -> vector * instream
   val input
                  : instream -> vector
   val input_all
   val input_noblock : instream -> (vector * instream) option
   val input1
                   : instream -> elem option * instream
   val input_n
                    : instream * int -> vector * instream
   val end_of_stream : instream -> bool
   val get_reader : instream -> PrimIO.reader
```

```
val open_out: string -> outstream
val mk_outstream : PrimIO.writer * string -> outstream
val close_out : outstream -> unit
val output : (outstream * vector) -> unit
val output1 : (outstream * elem) -> unit
val flush_out : outstream -> unit
val getpos_out : outstream -> int
val setpos_out : outstream * int -> unit
val get_writer: outstream -> PrimIO.writer
```

end

Each instream f can be viewed as a sequence of "available" elements (the buffer or sequence of buffers) and a mechanism (the **reader**) for obtaining more. After an operation (v, f') = input(f) it is guaranteed that v is a prefix of the available elements. In a "truncated" instream, there is no mechanism for obtaining more, so the "available" elements comprise the entire stream. In a "terminated" outstream, there is no mechanism for outputting more, so any output operations will raise the Io exception.

PrimIO

Every instance of STREAM_IO is built over an instance of PRIM_IO.

 \mathbf{elem}

A single element (member of a stream).

vector

A sequence of elements, just as in PRIM_IO.

$f = \operatorname{open_in}(s)$

Opens a file named s as a stream f. "Default" implementations of STREAM_IO will support **open_in**; other implementations may choose to support only **mk_instream**, raising Io on **open_in**.

$f = \mathbf{mk_instream}(r, s)$

Create a buffered stream f from a reader r. For purposes of identifying f to the user if exceptions occur, use the name s. In r, read_block, reada_block, and block must not all be NONE or an Io exception will be raised. (Most users will normally use open_in instead.)

$close_in(f)$

Truncate f, and release operating system resources associated with the underlying file (if any).

 $g = \operatorname{setposin}(f, i)$

Now g is a new instream starting from position i of f. f may or may not

be truncated, depending on whether the setpos request can be satisfied within the buffer. (Nondeterministic behavior! is that bad?) Not always supported.

getposin(f)

Return the current position (elements since beginning of file, starting at 0) of f. Not always supported.

 $(v, f') = \mathbf{input}(f)$

If any elements of f are available, return sequence v of one or more elements and the "remainder" f' of the stream. If f is at end of file, return the empty sequence. Otherwise read from the operating system (which may block) until one of those conditions occurs.

$v = input_all(f)$

Return the vector v of all the elements of f up to end of stream. Semantically equivalent to:

where ^ is the concatenation operator on element vectors.

$(v, f') = input_noblock(f)$

If any non-empty sequence v of f is available or can be read from the operating system without blocking, return SOME(w, f') where w is any non-empty prefix of v, and f' is the "rest" of the stream. Otherwise return NONE.

$(c, f') = \mathbf{input1}(f)$

If at least one element e of f is available, return (SOME(e), f'). If f is at end of file, return the NONE. Otherwise read from the operating system (which may block) until one of those conditions occurs. Semantically equivalent to:

 $(v, f') = \mathbf{input_n}(f, n)$

If at least n elements remain before end of stream, return the first n elements. Otherwise, return the (possibly empty) sequence of elements

remaining before end of stream. Blocks if necessary. (This was the behavior of the **input** function in the 1989 *Definition of Standard ML*.) Semantically equivalent to:

$end_of_stream(f)$

False if any characters are available in f; true if f is at end of stream. Otherwise reads (perhaps blocking) until one of these conditions occurs. Exactly equivalent to (size(input f)=0).

$get_reader(f)$

Extract the underlying reader from f. Truncates f. Careful users should probably do something like

```
let val r = get_reader f
    val v = input_all f
    in ...
end
```

so as to obtain the elements v already in the buffer before doing anything with r.

$f = open_out(s)$

Open (for writing) a file named s (creating it if necessary) as an outstream f. Not always supported.

$f = \mathbf{mk_outstream}(w, s)$

Create a buffered outstream f from a writer w. For purposes of identifying f to the user if exceptions occur, use the name s. In w, write_block, writea_block, and block must not all be NONE or an Io exception will be raised.

$close_out(f)$

Flush f's buffer, terminate f, then close the underlying writer (releasing operating-system resources associated with it).

$flush_out(f)$

Flush f's buffer: that is, make the underlying file reflect any previous **output** operations.

output(f, v)Write the sequence v to f.

```
{f output1}(f,x)
```

Write the element x to f.

```
get\_writer(f)
```

Get the underlying writer associated with f. Flushes and terminates f.

```
getpos_out(f)
```

Give the current position of f in the underlying file. Not always supported.

```
setpos_out(f, i)
```

Set the current position of f in the underlying file to i. Flush f if necessary. Not always supported.

Any prefix of the concatenation of previous writes (since the last setpos or flush) may be reflected in the underlying file.

Operations marked *Not always supported* may fail on some streams or in some instantiations of the STREAM_IO signature, raising Io{syserror = OS.noError,...}. (Should we make a special OS.notSupported?)

Rules: The following expressions are all guaranteed **true**, if they complete without exception.

Input is semi-deterministic: **input** may read any number of elements from f the "first" time, but then it is committed to its choice, and must return the same number of elements on subsequent reads from the same point.

```
let val (a,_) = input f
    val (b,_) = input f
    in a=b
end
```

Closing a stream just causes the not-yet-determined part of the stream to be empty:

```
let val (a,f') = input f
    val _ = close_in f
    val (b,_) = input f
    in a=b andalso end_of_stream f'
end (* must be true *)
```

If a stream has already been at least partly determined, then input cannot possibly block:

```
let val a = input f
in case input_noblock f
    of SOME a => a=b
        | NONE => false
end (* must be true *)
```

Note that a successful **input_noblock** does not imply that more characters remain before end-of-file, just that reading won't block.

Closing a stream guarantees that the underlying reader will never again be accessed; so input can't possibly block:

(case (close f; input_noblock f) of SOME _ => true | NONE => false)

The end_of_stream test is equivalent to input returning an empty sequence:

let val (a,_) = input f in (size(a)=0) = (end_of_stream f) end

Unbuffered I/O That is, if chunksize=1 in the underlying reader, then **input** operations must be unbuffered:

```
let val f = mk_instream(reader)
    val (a,f') = input(f,n)
    val PrimIO.Rd{chunksize,...}=get_instream f
    in chunksize>1 orelse end_of_stream f'
end
```

Though input may perform a read(k) operation on the reader (for $k \ge 1$), it must immediately return all the elements it receives. However, this does not hold for partly determined instreams:

```
let val f = mk_instream(reader)
    val _ = do_input_operations_on(f)
    val (a,f') = input(f,n)
    val PrimIO.Rd{chunksize,...}=get_instream f
    in chunksize>1 orelse end_of_stream f' (* could be false*)
end
```

because in this case, the stream f may have accumulated a history of several responses, and **input** is required to repeat them one at a time.

Similarly, output operations are unbuffered if chunksize=1 in the underlying writer. Unbuffered output means that the data has been written to the underlying writer by the time **output** returns.

Don't bother the reader input must be done without any operation on the underlying reader, whenever it is possible to do so by using elements from the buffer. This is necessary so that repeated calls to **end_of_file** will not make repeated system calls.

This rule could be formalized by defining a "monitor:"

and making statements such as:

```
let val {rd,chars_read,op_count} = monitor(reader)
  val f = mk_instream(rd)
  val (f',n_elems) = do_things_counting_elements(f)
  val p1 = getpos_in f'
  val c1 = !chars_read
  val ops = !op_count
  val _ = input f'
  in not ((n_elems < c1) andalso (!op_count > ops))
end
```

but perhaps this level of detail is unnecessary.

Multiple end of file In Unix, and perhaps in other operating systems, there is no notion of "end of stream." Instead, by convention a **read** system call that returns zero bytes is interpreted to mean end of stream. However, the next read to that stream could return more bytes. This situation would arise if, for example,

- the user hits cntl-D on an interactive tty stream, and then types more characters;
- input reaches the end of a disk file, but then some other process appends more bytes to the file.

Consequently, the following is not guaranteed to be true:

```
let val z = end_of_stream f
    val (a,f') = input f
    val x = end_of_stream f'
    in x=z (* not necessarily true! *)
end
```

The "don't bother the reader" rule, combined with the definition of **end_of_stream**, guarantees that

```
end_of_stream(f) = end_of_stream(f).
```

Implementors should beware that an empty buffer sometimes means end of stream, and sometimes not; I found an extra boolean variable necessary to keep track.

6 StreamIO

The functor StreamIO layers a buffering system on a primitive IO module:

```
functor StreamIO(structure PrimIO : PRIM_IO
    structure Vec: MONO_VECTOR
    structure Arr: MONO_ARRAY
    val some_elem : PrimIO.elem
    sharing type PrimIO.elem = Arr.elem = Vec.elem
    sharing type PrimIO.vector=Arr.vector=Vec.vector
    sharing type PrimIO.array=Arr.array
    ) : STREAM_IO = ...
```

The Vec and Arr structures provide Vector and Array operations for manipulating the vectors and arrays used in PrimIO and StreamIO. The element some_elem is used to initialize buffer arrays; any element will do.

If **flush_out** finds that it can do only a partial write (i.e., **writea_block** or a similar function returns a "number of elements written" less than its "nelems" argument) then **flush_out** must adjust its buffer for the items written and then raise an Io exception, in such a way that if the next (or any future) **flush_out** is successful, no data will have been lost or twice-written.

The same rule applies to output (etc.) if it calls flush_out.

What is the behavior of the **Stream IO** primitives if a user interrupt occurs? Reppy thinks that losing information is preferable to printing output twice. This should be cogitated and clarified.

Implementation notes:

The previous section gives the specification of **StreamIO** behavior. Here are some suggestions for efficient performance:

- Operations on the underlying readers and writers (**read_block**, etc.) are expected to be expensive (involving a system call, with context switch).
- Small input operations can be done from a buffer; the **read_block** or **read_nonblock** operation of the underlying reader can replenish the buffer when necessary.
- Keep the position of the beginning of the buffer on a multiple-of-**chunksize** boundary, and do **read** or **write** operations with a multiple-of-**chunksize** number of elements.
- For very large input_all or input_n operations, it is (somewhat) inefficient to read one chunksize at a time and then concatenate all the results together. Instead, it is good to try to do the read all in one large system call; that is, read_block(n). However, in a typical implementation of read_block this requires pre-allocating a vector of size n. If the user does input_all() or input_n(maxint), either the size of the vector is not known a priori or the allocation of a much-too-large buffer is wasteful. Therefore, for large input operations, query the size of the reader using size, subtract the current position, and try to read that much. But one should also keep things rounded to the nearest chunksize.

Since size is permitted to be inaccurate—in particular, some implementations may just return 0—something reasonable should be done in any case.

- Similar suggestions apply to very large **output** operations. Small outputs go through a buffer; the buffer is written with **writea_block**. Very large outputs can be written directly from the argument string using **write_block**.
- But how should the current buffer position be remembered? Either a **getpos** every time **size** is called, or a **getpos** when **mk_instream** is first called, followed by careful maintenance of the position of the beginning of the buffer. (Remember, **mk_instream** might be called only after the underlying reader has been moved away from the beginning position.)
- A lazy function instream can (should) be implemented as a sequence of immutable (vector) buffers, each with a mutable ref to the next "thing," which is either another buffer, the underlying reader, or an indication that the stream has been truncated.
- The **input** function should return the largest sequence that is most convenient; usually this means "the remaining contents of the current buffer."
- To support non-blocking input, use **read_noblock** if it exists, otherwise do **can_input** followed (if appropriate) by **read_block**.
- To support blocking input, use **read_block** if it exists, otherwise do **read_noblock** followed (if would block) by **block** and then another **read_noblock**.
- To support lazy functional streams, **reada_block** and **reada_noblock** are not useful; they are included only for completeness.
- Setpos_in, if setpos-ing forward, might choose to follow the buffer sequence, and can perhaps satisfy the setpos request without any underlying reader operation.
- Getpos_in, in some implementations, can tell the position without a system call, if it knows the position of the beginning of the buffer and the current position within the buffer.
- writea_block should, if necessary, be synthesized from write_block, and vice versa. Similarly for writea_noblock and write_noblock; reada_noblock and read_noblock; reada_block and read_block.

7 IO functor

The precise definition of "conventional" streams (IO signature) is in terms of "lazy functional" streams (STREAM_IO). The functor IO is provided:

functor IO(structure S : STREAM_IO) : IO = ...

The structures **BinIO** and **TextIO** are (presumably) built using separate applications of this functor (though TextIO is then enhanced with **std_in**, etc.), but users may apply the **StreamIO** and **IO** functors to make streams data types other than char and byte.

The semantics of **IO** are simple enough that it is sufficient to give a reference implementation.

```
functor IO(structure S : STREAM_IO) : IO =
let abstraction I =
struct
   structure StreamIO = S
   type instream = S.instream ref
   type outstream = S.outstream ref
   type elem = S.elem
   type vector = S.vector
   val mk_instream = ref
  val get_instream = !
  val set_instream = op :=
   val mk_outstream = ref
   val get_outstream = !
   val set_outstream = op :=
   val open_in = ref o S.open_in
   fun end_of f = if S.end_of_stream f then f else end_of(#2(S.input f))
  fun close_in(r as ref f) = (S.close_in f; r := end_of f)
   fun setpos_in(r as ref f, i) = r := S.setpos_in(f,i)
   val getpos_in = S.getpos_in o !
   fun input(r as ref f) = let val (v, f') = S.input f in r:=f'; v end
  fun input_all(r as ref f) = let val v = S.input_all f
                                in r := end_of f; v end
  fun input_noblock(r as ref f) =
      let val (v,f') = S.input_noblock f in r:=f'; v end
   fun input1(r as ref f) = let val (v,f') = S.input1 f in r:=f'; v end
   val end_of_stream = S.end_of_stream o !
   fun lookahead(ref f) = #1(S.input1 f)
   val open_out = ref o S.open_out
  val close_out = S.close_out o !
  fun output(ref f, v) = S.output(f, v)
  fun output1(ref f, x) = S.output1(f,x)
   val getpos_out = S.getpos_out o !
```

```
fun setpos_out(ref f, i) = S.setpos_out(f,i)
val flush_out = S.flush_out o !
end
in I
end
Note that the instream and outstream types are abstract.
Some consequences of this definition:
The end_of_stream semantics are
fun end_of_stream (f as ref ff) = StreamIO.end_of_stream ff
This implies
let val x = end_of_stream f
val y = end_of_stream f
```

in x=y (* guaranteed true *)

Furthermore, second call to end_of_stream is guaranteed not to do any system call; this is a consequence of the "Don't bother the reader" semantics of StreamIO.input.

However, reading past end of stream is possible via input; the semantics may be straightforwardly derived from the semantics of StreamIO.input.

The output operations (which were not lazy functional to begin with) are even more similar between STREAM_IO and IO. The only purpose of the extra ref in IO is to allow "output redirection."

8 Random access reading/writing to the same stream

Instreams are instreams, outstreams are outstreams, and ne'er the twain shall meet. At least, not face to face. However, competent users can construct many things from the layered functors.

Here's an example: reading and writing to the same random-access file without re-opening it.

1. Open the file for reading, and for writing; extract the underlying reader and writer, discarding the buffering layer.

```
val reader = TextIO.StreamIO.get_reader (TextIO.StreamIO.open_in name)
val writer = TextIO.StreamIO.get_writer (TextIO.StreamIO.open_out name)
```

2. Do some buffered writes; then discard the buffering layer.

```
let val out = TextIO.mk_outstream(TextIO.StreamIO.mk_outstream(writer,name))
in TextIO.setpos_out(out,some_pos);
    output(out,"Hello ");
    output(out,"World\n");
    flush_out out
end
```

3. Do some buffered reads; then discard the buffering layer.

```
let val inf = TextIO.mk_instream(TextIO.StreamIO.mk_instream(reader,name))
in TextIO.setpos_in(inf,another_pos);
    input inf;
    input inf
end
```

4. And so on. It's cheap and easy to do **mk_instream** whenever switching between reading and writing.

9 Loose ends

What about opening files for append?

What about user (and other) interrupts during buffered I/O operations? Should setpos positions be abstract? How should positions work in translated readers or writers?